

ROADSHOW #2 Precise Positioning and localization inside Tunnel Rennsteig

Hi-Drive Webinar 02 – 22.09.2023

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Agenda

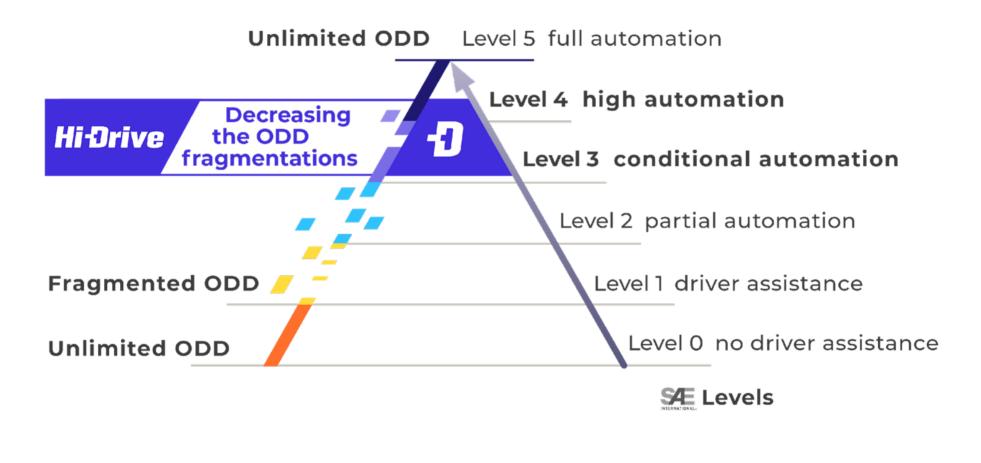
- **1. Hi Drive Use Case Description**
- 2. Tunnel Rennsteig Information
- 3. Challenges
- 4. Valeo Motorway Chauffeur
- 5. Conclusion



Hi Drive Use Case Description

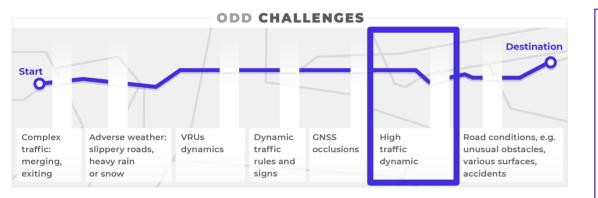
Push Towards Higher Automation

Hi-Drive



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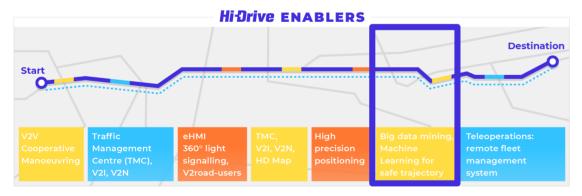
Defragmentation of the Operational Design Domain



----- ODD (Operational Design Domain) A

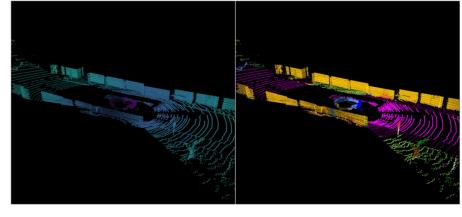
Automated Driving Manual Driving

····· Continuous Automated Driving in cybersecure, interoperable, interactive and user-aware vehicles

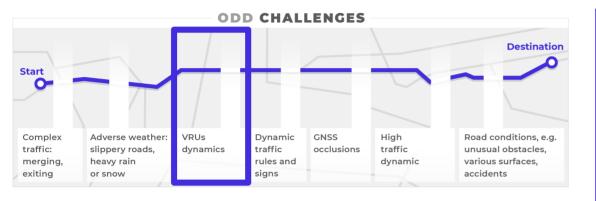


Valeo's Contribution in Machine Learning

Comprehensive perception for robust and safe navigation will be achieved through **Point cloud segmentation**.

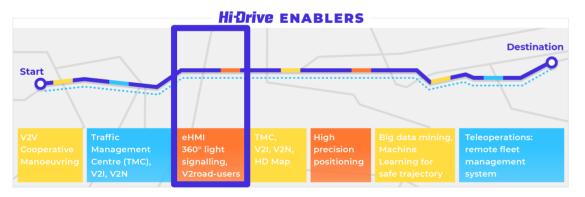


Defragmentation of the Operational Design Domain



ODD (Operational Design Domain) — Automated Driving — Manual Driving

····· Continuous Automated Driving in cybersecure, interoperable, interactive and user-aware vehicles



Valeo's Contribution in Light Signalling

Communication and interaction with road users through lighting systems (Valeo VLS).

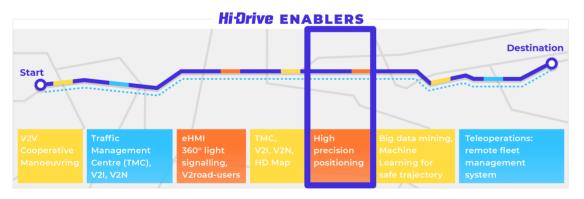


Defragmentation of the Operational Design Domain



ODD (Operational Design Domain) Automated Driving

..... Continuous Automated Driving in cybersecure, interoperable, interactive and user-aware vehicles



Valeo's Contribution in Localization

Precise Vehicle Localization providing an accurate vehicle positioning system to eliminate GNSS blackspots







Tunnel Rennsteig Information

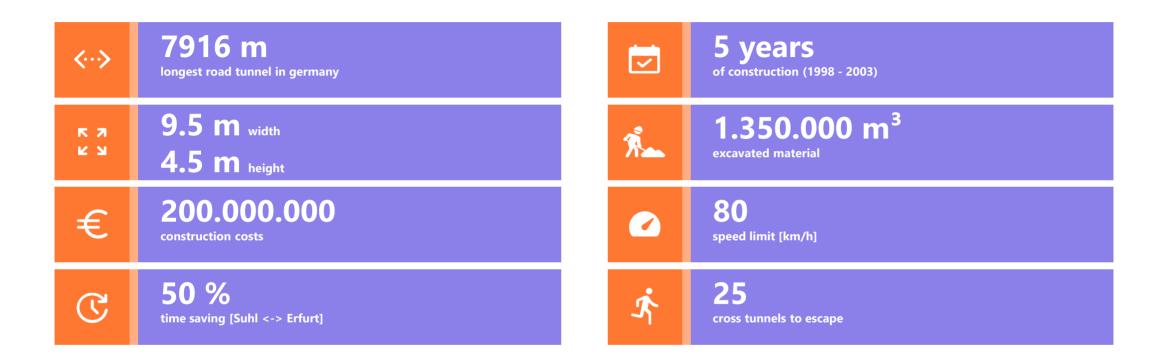
Location





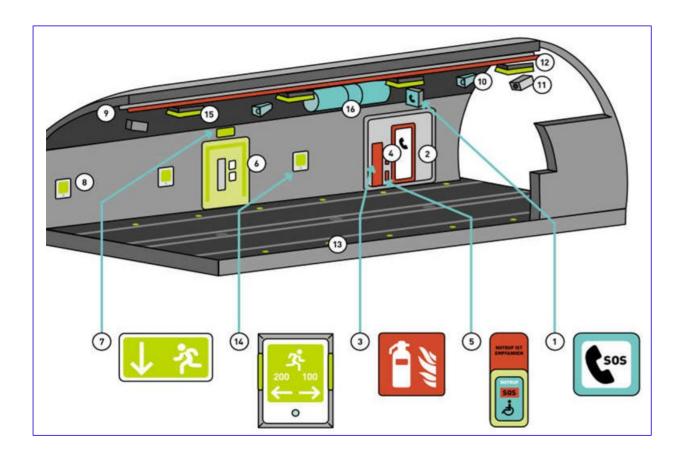
Hi Drive

Key facts



Hi-Drive

Safety facilities

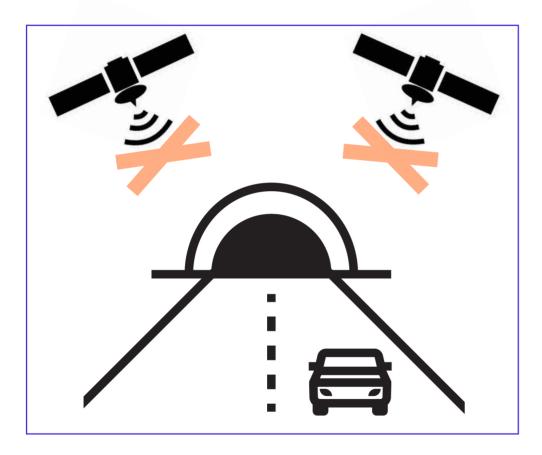


1	signaling emergency call device	
2	emergency call cabin	
3	fire extinguisher	
4	fire alarm	
5	handicapped accessible call button	
6/7	emergency exit	
8	escape route sign	
9	antenna cable for radio reception	
10	speakers	
11	video camera	
12	fire detector	
13	markings	
14	orientation lighting in case of fire	
15	illuminating device	
16	venting system	





Challenges



GNSS denied area

- Short interruptions

 e.g. occlusions from buildings and bridges
 Valeo's Drive4U system works
- Tunnel Rennsteig has >6 min. of **no GNSS signal**
- Navigation systems give up
- Limitations in position accuracy arise



Poor camera view

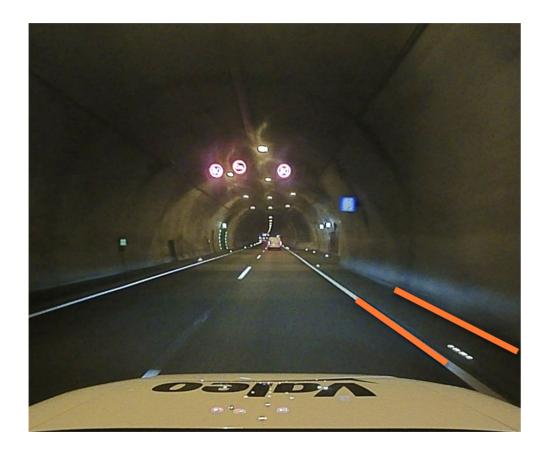
• Due to artificial illumination, positioning by camera gets tricky



Dark/Light Transition

• Sharp contrasting lighting when entering and exiting the tunnel

Hi Drive



Limited roadway width

- Restricted geometry: lateral deviations due to incorrect steering leads easily to collisions and increase the risk of accidents
- no emergency lane
- only a small pavement [width 0.25 meters (9.8 inch)]
- stopping is difficult and dangerous

High risk - a history of devastating accidents:



https://www.mdr.de/nachrichten/thueringen/nord-thueringen/eichsfeld/unfall-sperrung-heidkopftunnel-verletzte-100.html

Hi:**D**rive

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Maneuvering in case of fire

 Main risk with using Automated cars in tunnels is that they may not operate in a safe manner in case of fire [1]

[1] https://www.loteconsulting.com/documents/Safety_Tunnels.pdf Image:https://www.insuedthueringen.de/inhalt.auto-geraet-in-brand-rennsteig-tunnel-nach-unfall-gesperrt. 454ed08f-adeb-46c2-b833-8c32fe24e11c.html



Temperature gradient

- Windshield Fogging in road tunnels due to water condensation
- Also tricky for cameras!



Non-standardized Tunnels

• Different infrastructure standards for different tunnels



Different road surfaces (snow, rain)



https://www.google.com/url?sa=i&url=https%3A%2F%2Funsplash.com%2Fs%2Fphotos%2Fwetroad&psig=AOvVaw3_u5v9SCK6YT9U1nISms3k&ust=1683276254572000&source=images&cd=vfe&ved= 0CBEQ3YkBahcKEwjwg_f3otv-AhUAAAAHQAAAAAQEA





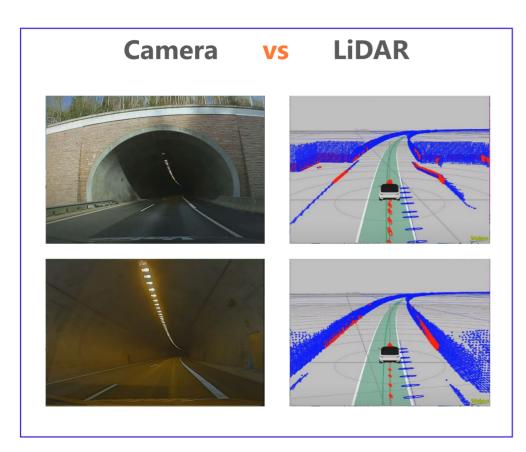
Valeo Motorway Chauffeur

Motorway Chauffeur



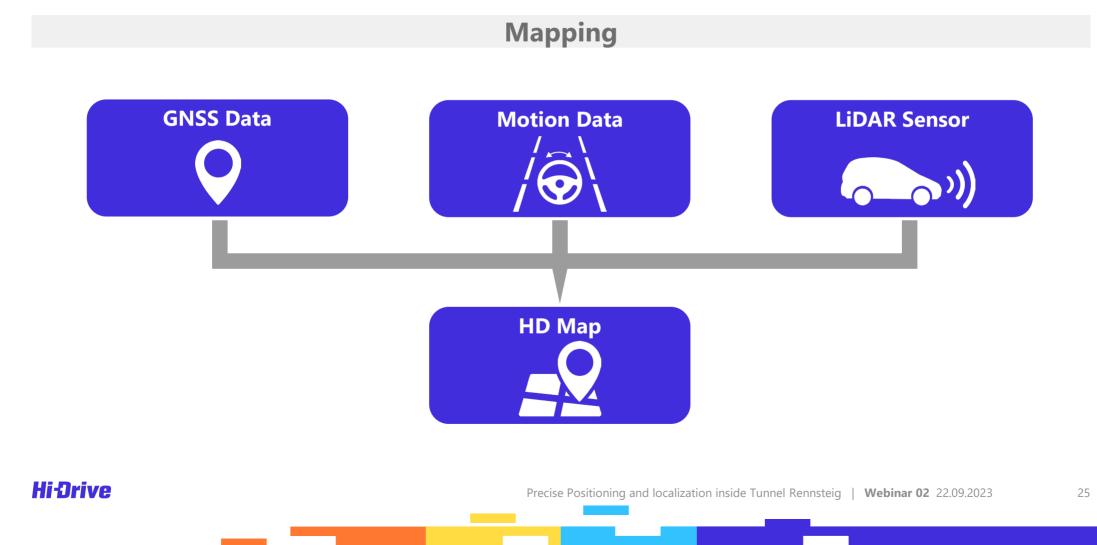
- ✓ Usable for all GNSS-denied areas
- Low ambient lighting conditions

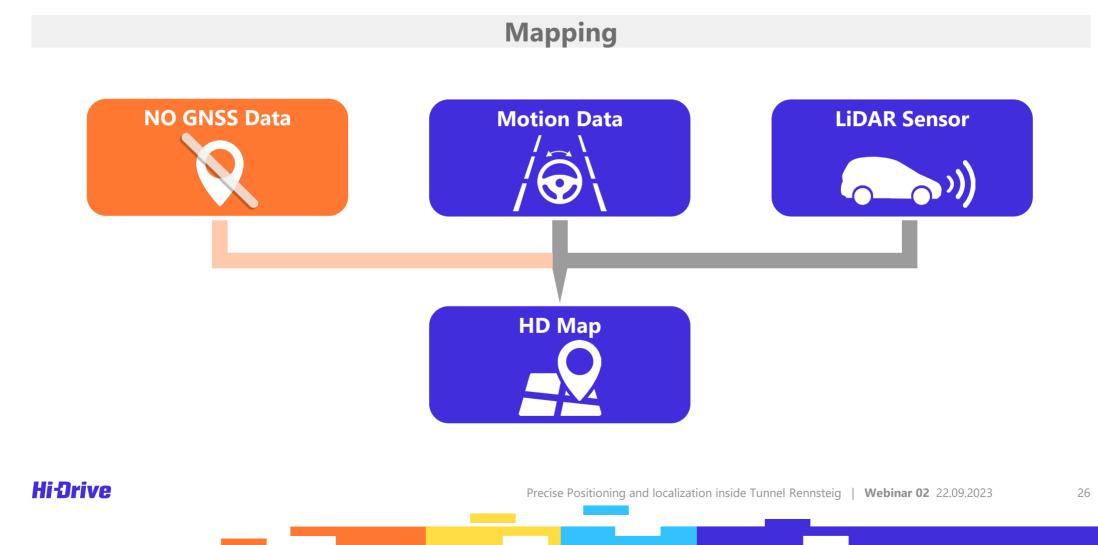
Motorway Chauffeur



	Camera	Lidar
Range Detection		
3D Detection		
Low light/darkness		
Weather condition		

I





Hi-Drive

Simultaneous Localization

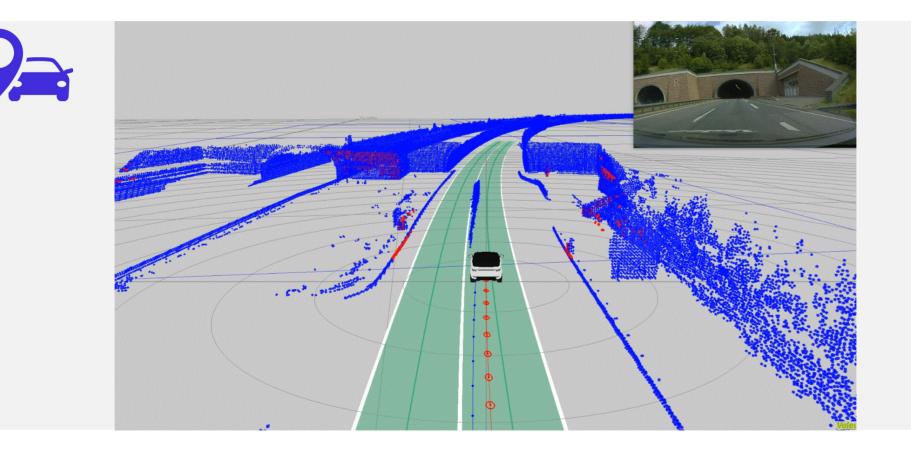


HD Map



Tunnel facilities used for map matching







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Conclusions

Conclusion

- Tunnels pose a large variety of challenges compared to most other ODDs.
- Precise Localization and Positioning inside the tunnel is difficult due to repeating structures.
- Using LiDAR and Inertial Measurement Unit, it is possible to create a High Definition (HD) map of the tunnel.
- This HD map is then to carry out map matching thereby accurately positioning the vehicle inside the tunnel.
- Using the above developed enabler, the Valeo Motorway Chauffeur is able to successfully drive through the biggest tunnel in Germany in complete autonomous mode.



THANK YOU FOR YOUR KIND ATTENTION.

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