

# ROADSHOW #2 Precise Positioning and localization inside Tunnel Rennsteig

Hi-Drive Webinar 02 – 22.09.2023

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# Agenda

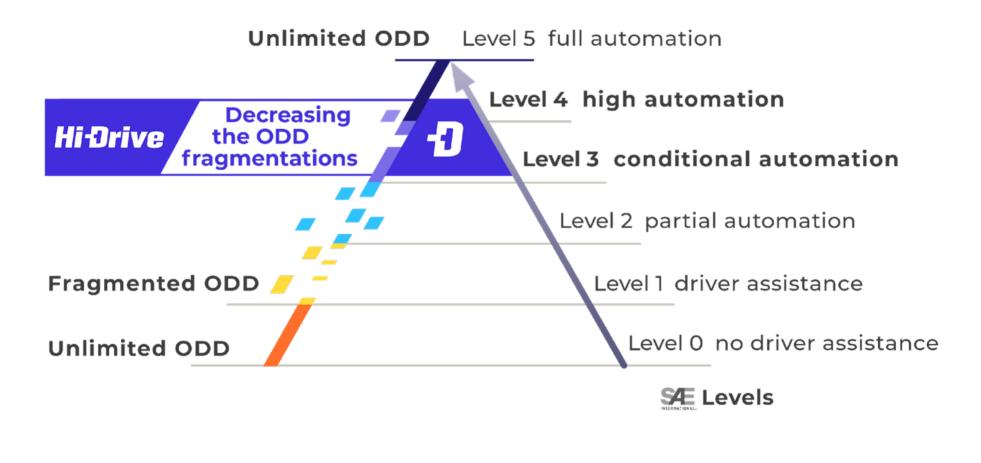
- **1. Hi Drive Use Case Description**
- 2. Tunnel Rennsteig Information
- 3. Challenges
- 4. Valeo Motorway Chauffeur
- 5. Conclusion



# Hi Drive Use Case Description

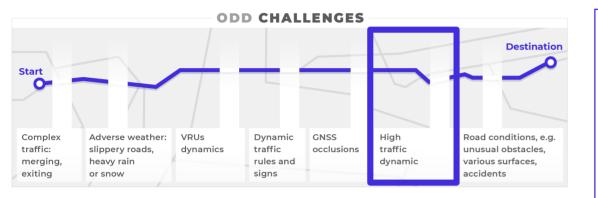
#### **Push Towards Higher Automation**

Hi-Drive



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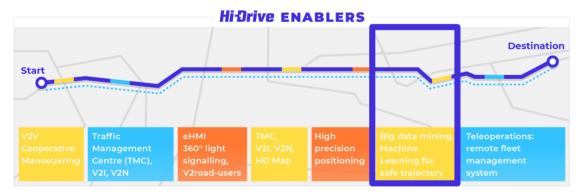
### **Defragmentation of the Operational Design Domain**



----- ODD (Operational Design Domain) A

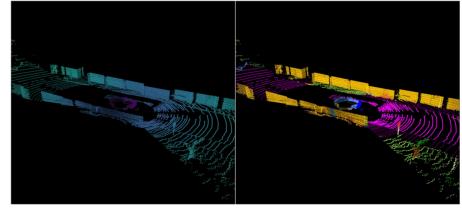
Automated Driving Manual Driving

····· Continuous Automated Driving in cybersecure, interoperable, interactive and user-aware vehicles



#### Valeo's Contribution in Machine Learning

Comprehensive perception for robust and safe navigation will be achieved through **Point cloud segmentation**.

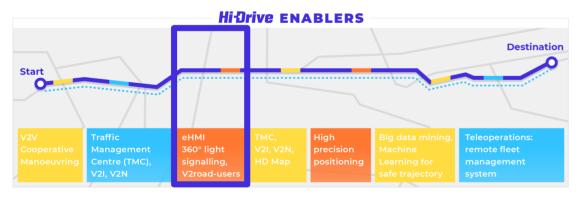


### **Defragmentation of the Operational Design Domain**



ODD (Operational Design Domain) — Automated Driving — Manual Driving

····· Continuous Automated Driving in cybersecure, interoperable, interactive and user-aware vehicles



#### Valeo's Contribution in Light Signalling

Communication and interaction with road users through lighting systems (Valeo VLS).

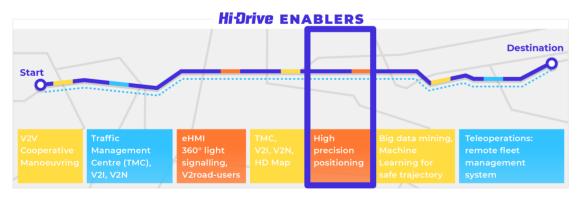


### **Defragmentation of the Operational Design Domain**



**ODD** (Operational Design Domain) Automated Driving

..... Continuous Automated Driving in cybersecure, interoperable, interactive and user-aware vehicles



#### Valeo's Contribution in Localization

**Precise Vehicle Localization** providing an accurate vehicle positioning system to eliminate GNSS blackspots



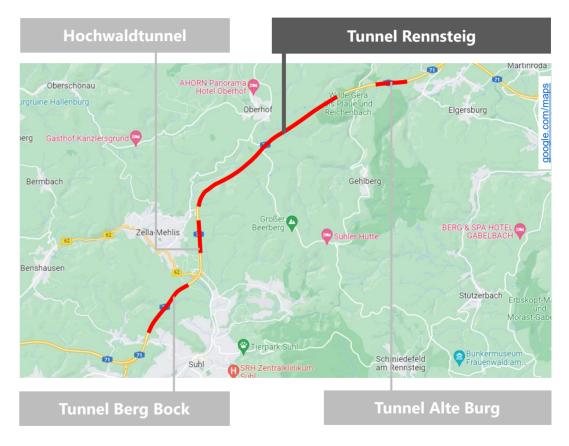




# **Tunnel Rennsteig Information**

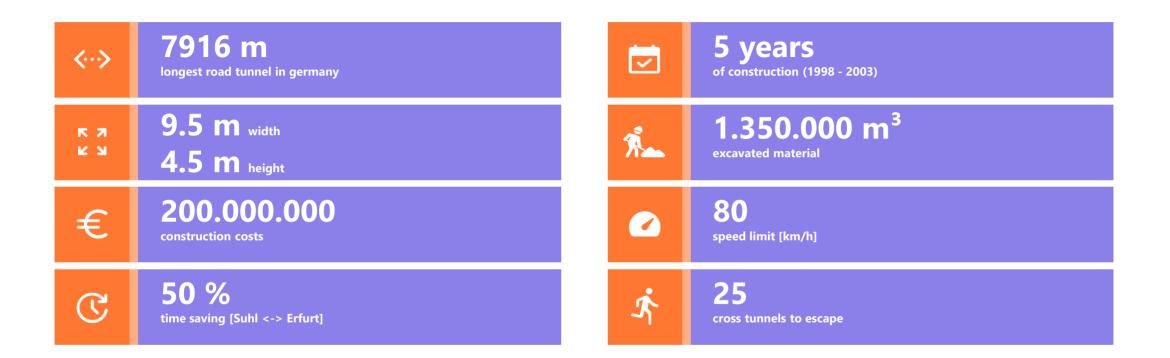
### Location





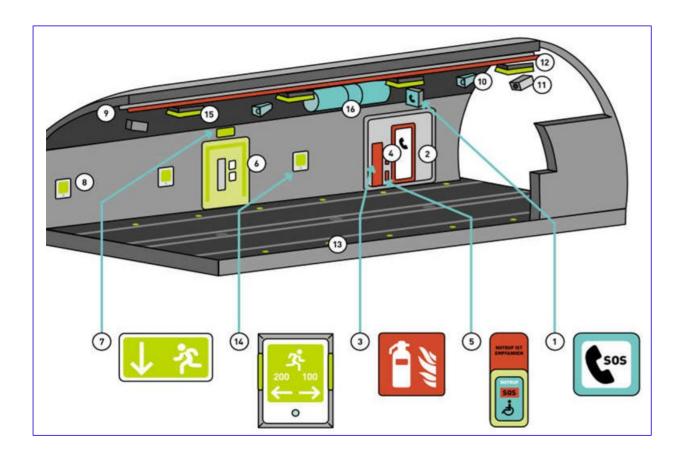
#### **Hi Drive**

### **Key facts**



#### **Hi**-Drive

# **Safety facilities**

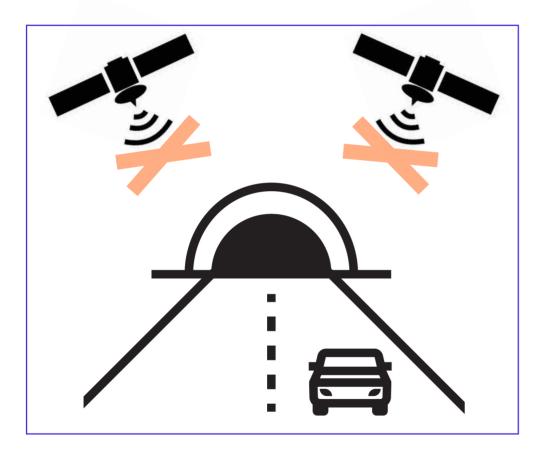


1	signaling emergency call device	
2	emergency call cabin	
3	fire extinguisher	
4	fire alarm	
5	handicapped accessible call button	
6/7	emergency exit	
8	escape route sign	
9	antenna cable for radio reception	
10	speakers	
11	video camera	
12	fire detector	
13	markings	
14	orientation lighting in case of fire	
15	illuminating device	
16	venting system	





# Challenges



#### **GNSS denied area**

- Short interruptions

   e.g. occlusions from buildings and bridges
   Valeo's Drive4U system works
- Tunnel Rennsteig has >6 min. of **no GNSS signal**
- Navigation systems give up
- Limitations in position accuracy arise



#### **Poor camera view**

• Due to artificial illumination, positioning by camera gets tricky



#### **Dark/Light Transition**

• Sharp contrasting lighting when entering and exiting the tunnel

#### **Hi Drive**



## Limited roadway width

- Restricted geometry: lateral deviations due to incorrect steering leads easily to collisions and increase the risk of accidents
- no emergency lane
- only a small pavement [width 0.25 meters (9.8 inch)]
- stopping is difficult and dangerous

# **High risk - a history of devastating accidents:**



https://www.mdr.de/nachrichten/thueringen/nord-thueringen/eichsfeld/unfall-sperrung-heidkopftunnel-verletzte-100.html

#### **Hi**:**D**rive

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## Maneuvering in case of fire

 Main risk with using Automated cars in tunnels is that they may not operate in a safe manner in case of fire [1]

[1] https://www.loteconsulting.com/documents/Safety\_Tunnels.pdf Image:https://www.insuedthueringen.de/inhalt.auto-geraet-in-brand-rennsteig-tunnel-nach-unfall-gesperrt. 454ed08f-adeb-46c2-b833-8c32fe24e11c.html



#### **Temperature gradient**

- Windshield Fogging in road tunnels due to water condensation
- Also tricky for cameras!



# Non-standardized Tunnels

• Different infrastructure standards for different tunnels



# Different road surfaces (snow, rain)



https://www.google.com/url?sa=i&url=https%3A%2F%2Funsplash.com%2Fs%2Fphotos%2Fwetroad&psig=AOvVaw3\_u5v9SCK6YT9U1nISms3k&ust=1683276254572000&source=images&cd=vfe&ved= 0CBEQ3YkBahcKEwjwg\_f3otv-AhUAAAAHQAAAAAQEA





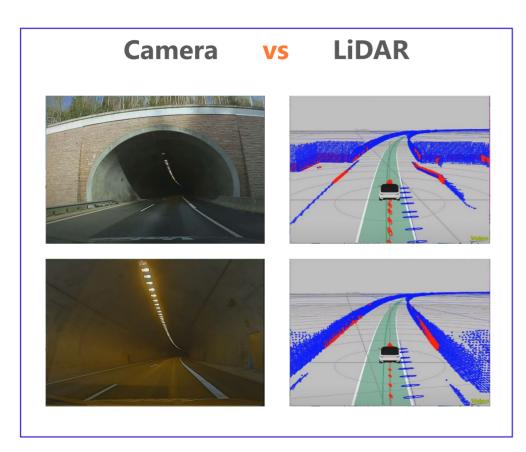
# Valeo Motorway Chauffeur

# **Motorway Chauffeur**



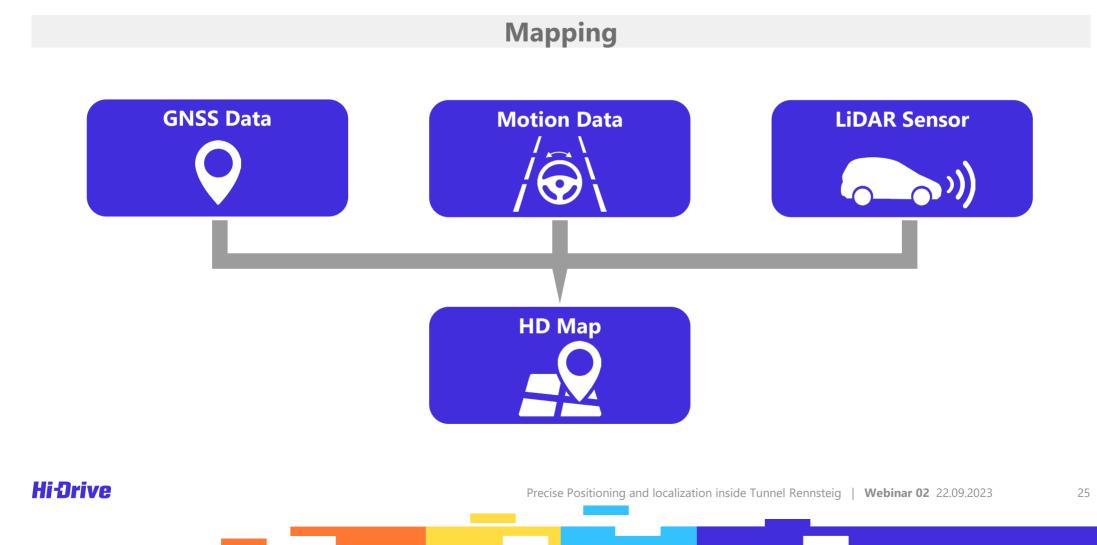
- ✓ Usable for all GNSS-denied areas
- Low ambient lighting conditions

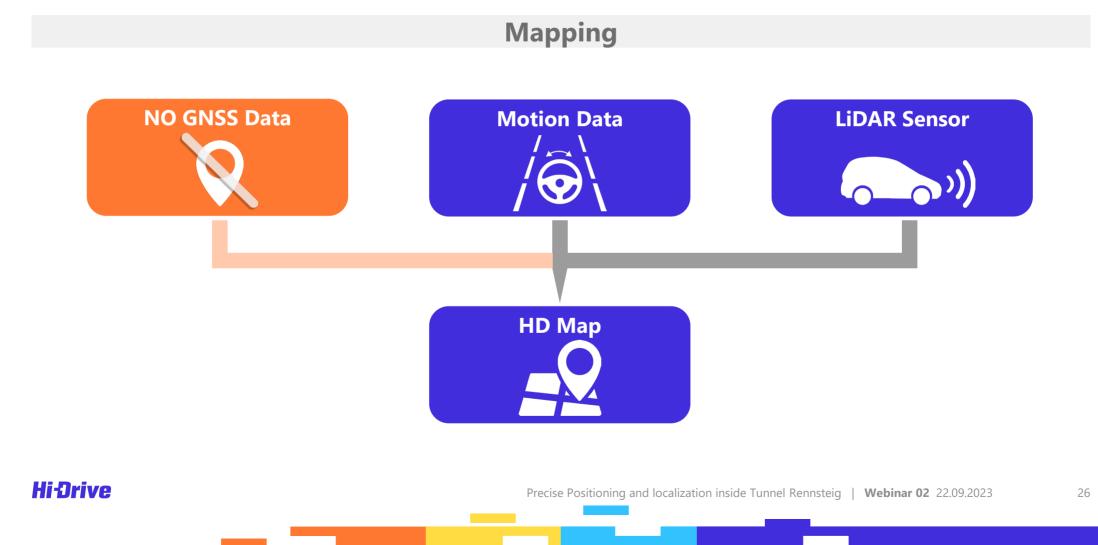
# **Motorway Chauffeur**



	Camera	Lidar
Range Detection		
3D Detection		
Low light/darkness		
Weather condition		

I





**Hi**-Drive

#### **Simultaneous Localization**

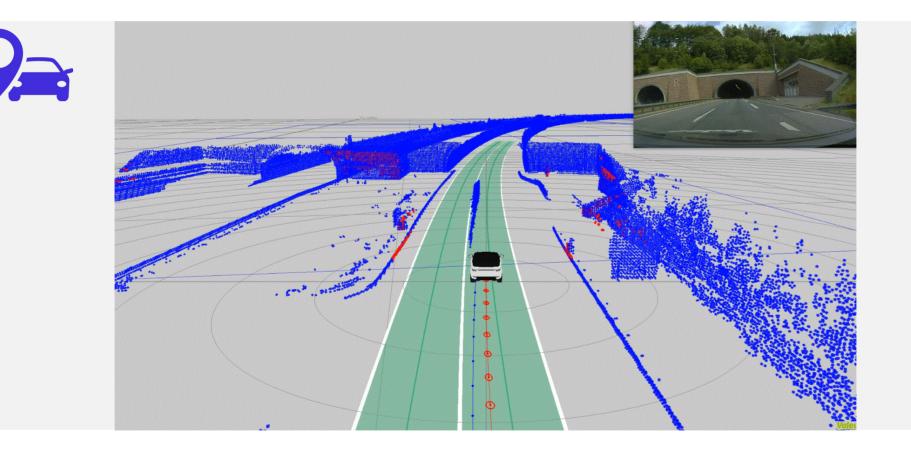


**HD** Map



# **Tunnel facilities used for map matching**







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# **Conclusion**s

#### **Conclusion**

- Tunnels pose a large variety of challenges compared to most other ODDs.
- Precise Localization and Positioning inside the tunnel is difficult due to repeating structures.
- Using LiDAR and Inertial Measurement Unit, it is possible to create a High Definition (HD) map of the tunnel.
- This HD map is then to carry out map matching thereby accurately positioning the vehicle inside the tunnel.
- Using the above developed enabler, the Valeo Motorway Chauffeur is able to successfully drive through the biggest tunnel in Germany in complete autonomous mode.



# THANK YOU FOR YOUR KIND ATTENTION.

#### Sanwardhini PANTAWANE

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